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# SODALITE: Software-Defined Execution and Optimization of In-Silico Clinical Trials in HPC with SODALITE Platform

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**HLRS**

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17.11.2020

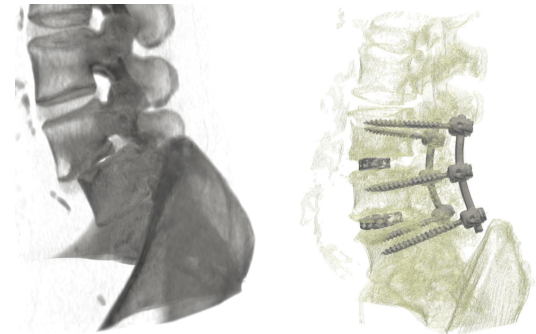
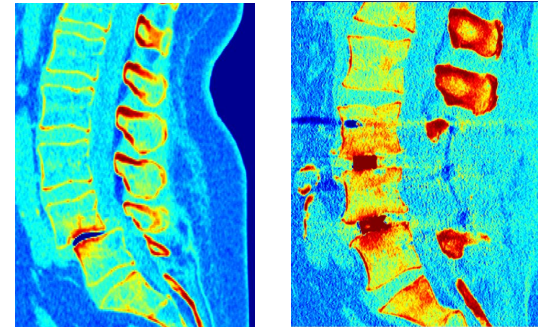
SC20



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# Medical Problem

- Some spinal conditions (e.g. disk displacement or prolapse) can only be treated **operatively**. A common treatment is mono- or bisegmental **fusion of the lumbar spine**.
- **A screw-rod fixation bone implant system** is used to fix parts of the lumbar spine.
- Biomechanical implant **development** is down to the present day **done on empirical basis**
- Selection of type, size and placement position is done **based on experience**
- **Implant optimization is complicated**



Before and after the fixation

# Virtual Clinical Trials

- Clinical trials with “*real*” patients are *time-consuming and expensive*.
- Every patient is *different and results can not be generalized*.
- **Virtual clinical trials reproduce clinical trials by means of simulation.**
  - Simulations are applied to virtual patient cohorts.
  - The UC represents research to advance this frontier.



Gamma nail



PFN-A



Gleitnagel: caudal

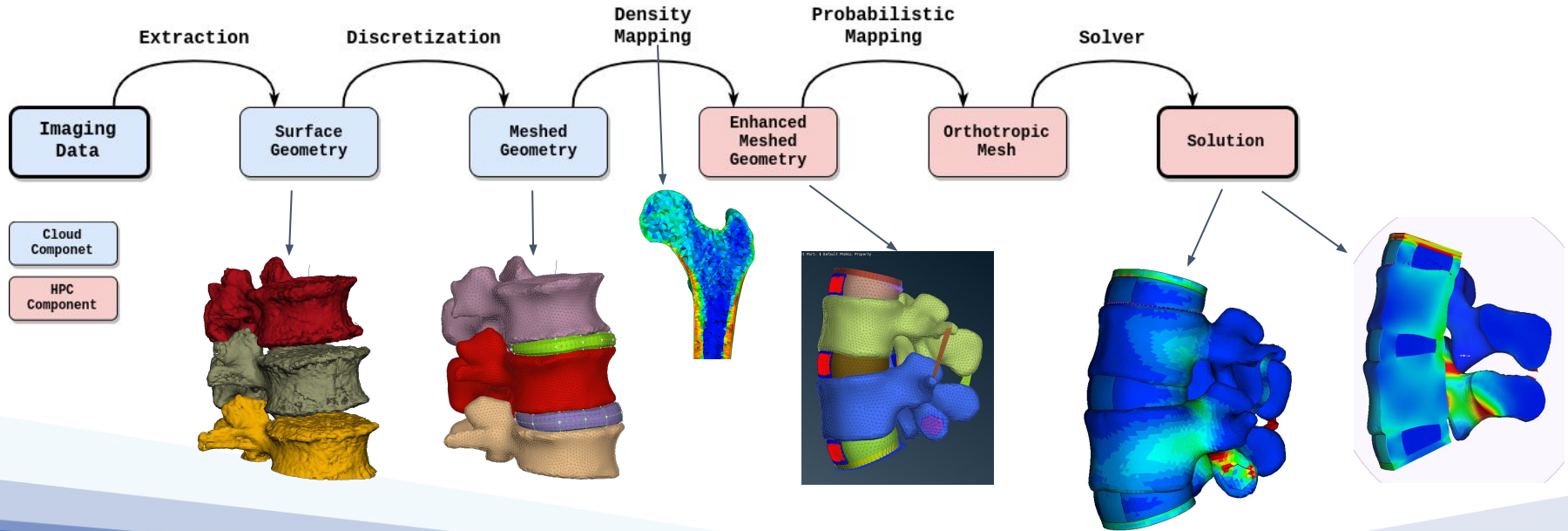


carnial



Targon PF

# Workflow



# Requirements



**A scientific workflow**, composed of multiple integrated components, with **efficient data processing** over **heterogeneous infrastructure**.

**Efficient development and failure management**. During a development cycle, a failed simulation should be **debugged** and **restarted** from the failed component, **not running the whole chain** again.

Data processing tasks are not finally defined and **may change and get more complicated** as the methodology of clinical virtual trials evolves: e.g. new data analytics component are likely to be introduced.

**Efficient uncertainty quantification** (currently done **manually**), which is not only needed in this special case but is widely sought after nowadays.

Evaluation in terms of **execution time/cost/power** over **various infrastructures and computing centers**.

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# Deployment problem



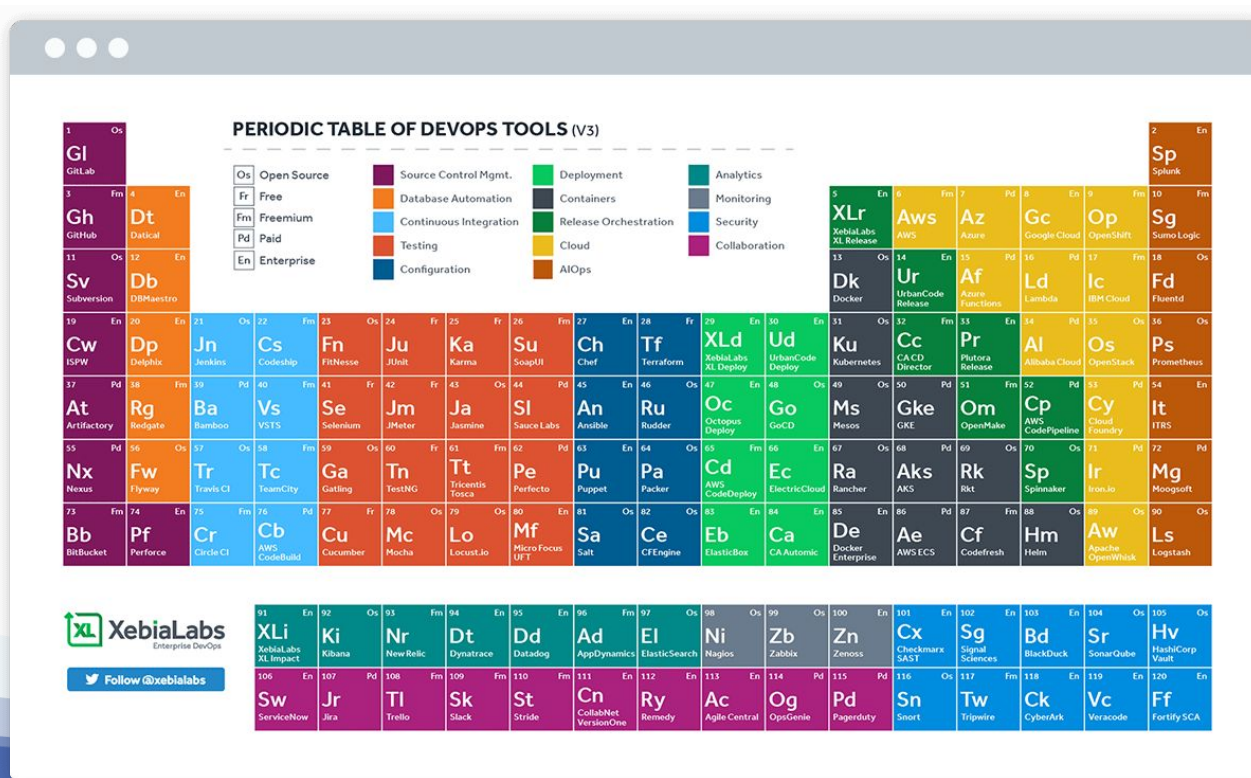
Current methodology of in-silico clinical trials in biomechanical simulations is **not productive**:

- Requires **effectiveness** in deployment, management and adaption to **different** IT-infrastructures (SC, Cloud, HW Heterogeneity)
- Requires **ease-of-use** for end users (medical device manufacturers or medical research institutes) and **reduced effort** of the developers.

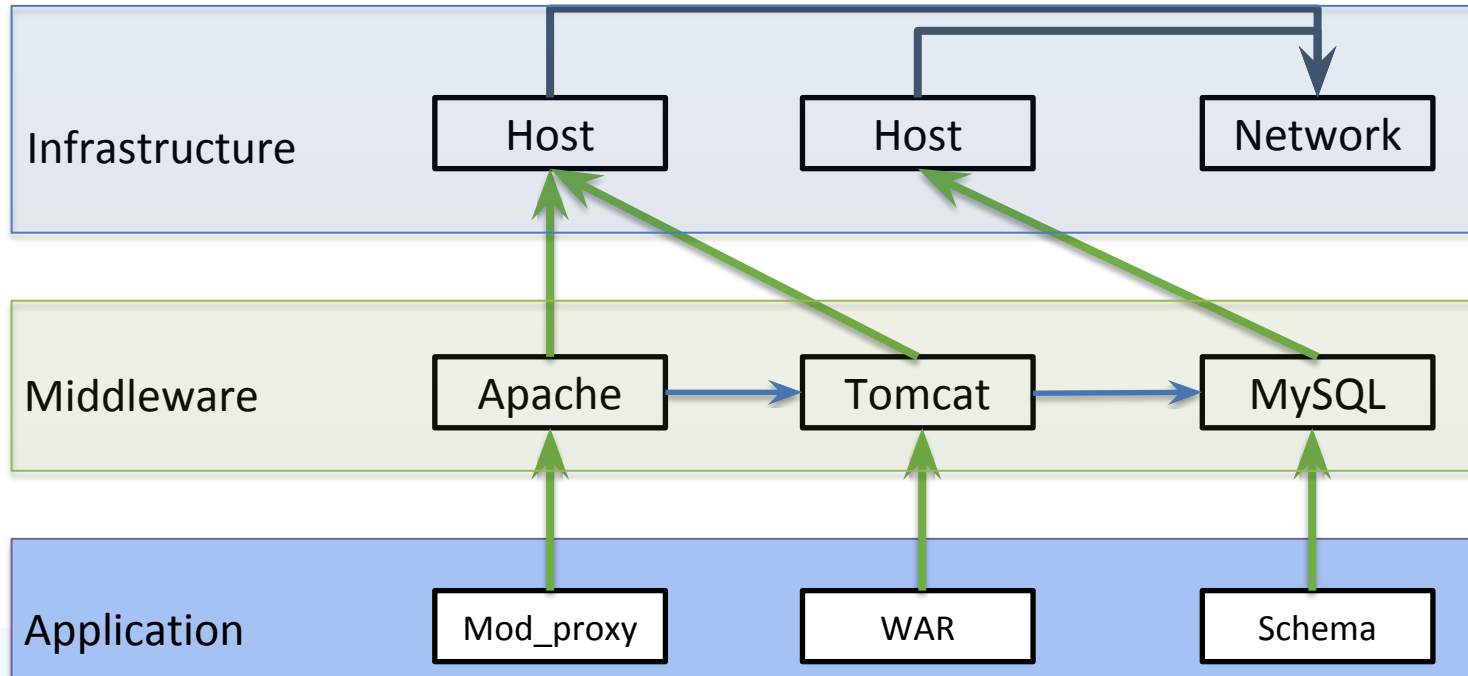
→ **DevOps** practices shall be adopted: IaC-based abstraction, flexibility, portability, reduced cost and effort



# The realm of DevOps tools



# Towards standard Infrastructure-as-Code (IaC)



→ **OASIS TOSCA** (Topology and Orchestration Specification for Cloud Applications) standard: quite complex (steep learning curve), no optimisation



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# SODALITE Vision



SODALITE provides tools to enable **simpler** and **faster development of IaC** and **deployment and execution of heterogeneous apps** in HPC, Cloud & SW defined computing environments.

Particular focus of SODALITE is on performance, quality, and manageability of the applications on the underlying infrastructures.

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# What SODALITE offers - a selection

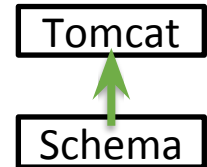


- Smart modeling
- Design-time application optimization
- Automated resource discovery (out-of-scope)
- Runtime optimization and control (out-of-scope)

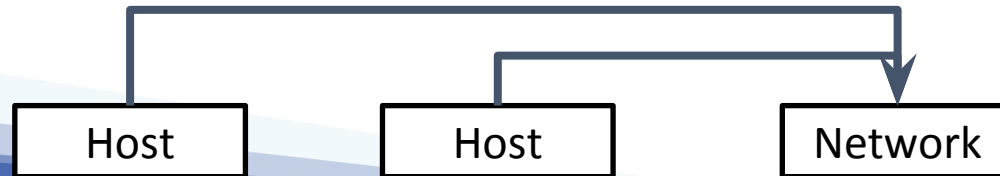
- Smart creation of deployment models through a textual and graphical DSL
- Editing is supported by an ontology-based reasoning mechanism that

- Checks the semantic validity of a model
  - E.g., it signals a problem if a requirement of a source node is not satisfied by a capability of the target node
- Enables the development of decision making tools, e.g.:
  - context-aware assistance of user at design-time
  - model enrichment taking into account domain knowledge

Schema requirement is not compatible with Tomcat capability



Two interacting hosts must be connected through a network



File Edit Diagram Navigate Search Run Window Help

Quick Access

hpc\_clinical.aadm

```

0 key-location:
7   type: string
8 email:
9   type: string
10 images-location:
11  type: string
12 modak-endpoint:
13  type: string
14 density-mapping-job-script:
15  type: string
16 probabilistic-mapping-job-script:
17  type: string
18 boundary-conditions-job-script:
19  type: string
20
21 node_templates:
22
23 hpc-wm-torque:
24  type: sodalite.nodes.hpc.wm.torque
25  attributes:
26    public_address: get_input: frontend-address
27    username: get_input: user
28    ssh-key: get_input: key-location
29
30 modak-instance:
31  type: sodalite.nodes.modak
32  properties:
33    endpoint: get_input: modak-endpoint
34
35 //image pulling
36
37 cadt-image:
38  type: sodalite.image_puller.singularity
39  properties:
40    output: "cad.t.sif"
41    image: "cad.t:1.0.0"
42    registry: "private"
43    certs_location: "certs"
44    images_location: "/mnt/nfs/home/kamil/images"
45  requirements:
46    host:
47      node: hpc-wm-torque
48
49 moduli-image:
50  type: sodalite.image_puller.singularity
51  properties:
52    output: "moduli.sif"
53    image: "moduli:1.0.0"
54    registry: "private"
55    certs_location: "certs"
56    images_location: "/mnt/nfs/home/kamil/images"
57  requirements:
58    host:
59      node: hpc-wm-torque

```

\*Clinical HPC Diagram

75%

Inputs

- frontend-address
- type: string
- user
- type: string
- key-location
- type: string
- email
- type: string
- images-location
- type: string
- modak-endpoint
- type: string
- density-mapping-job-script
- type: string
- probabilistic-mapping-job-script
- type: string
- boundary-conditions-job-script
- type: string

Diagram showing a workflow with nodes: torque, probabilistic-mapping-job, density-mapping-job-resu, singularity moduli-image, singularity code-aster-image, and job. Properties and requirements are shown for several nodes.

Properties for boundary-conditions-job-script:

```

name: boundary-conditions-job-script
workspace: ~/workspaces
enable_audit: true
env: <Complex Value>

```

Attributes for singularity code-aster-image:

```

public_address: org.sodalite
username: org.sodalite
ssh-key: org.sodalite

```

Properties for singularity moduli-image:

```

output: moduli.sif
image: moduli:1.0.0
registry: private
certs_location: certs
images_location: /mnt/nfs/home/kamil/images

```

IDE demo: <https://www.youtube.com/watch?v=8YC11JFSWC4>

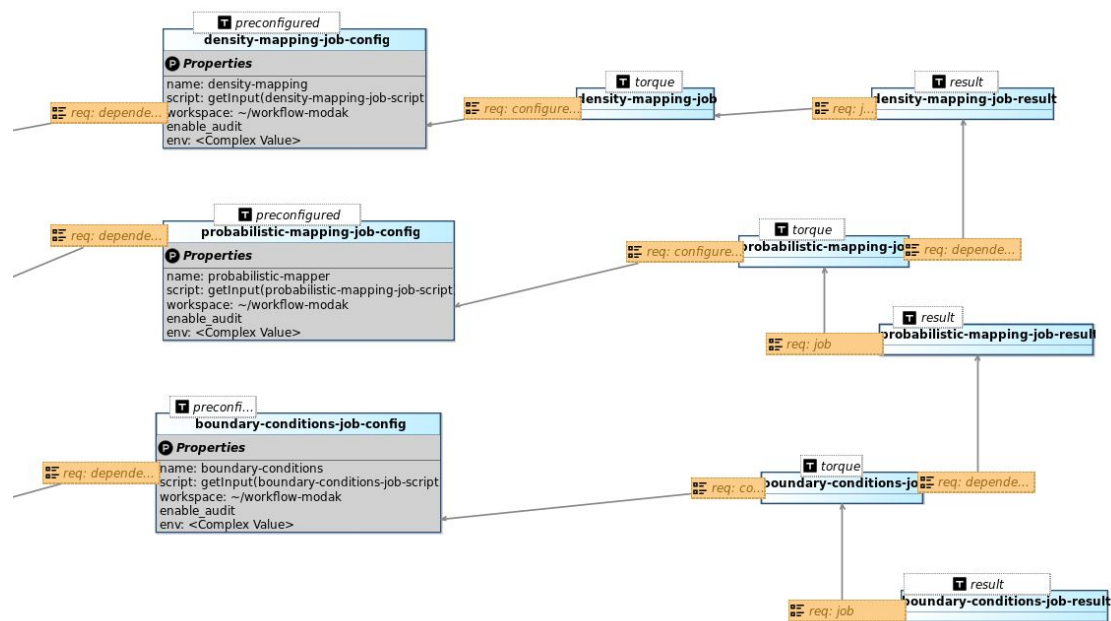
# Workflow modeling



```
density-mapping-job-config:  
type: sodalite.nodes.hpc.job.torque.preconfigured  
properties:  
  name: "density-mapping"  
  script: get_input(density-mapping-job-script  
  workspace: "~/workflow-modak  
  enable_audit  
  env: <Complex Value>  
  SINGULARITY_DIR: "/home/kamil/images"  
requirements:  
  host:  
    node: hpc-wm-torque
```

```
density-mapping-job:  
type: sodalite.nodes.hpc.job.torque  
requirements:  
  host:  
    node: hpc-wm-torque  
  configured_job:  
    node: density-mapping-job-config
```

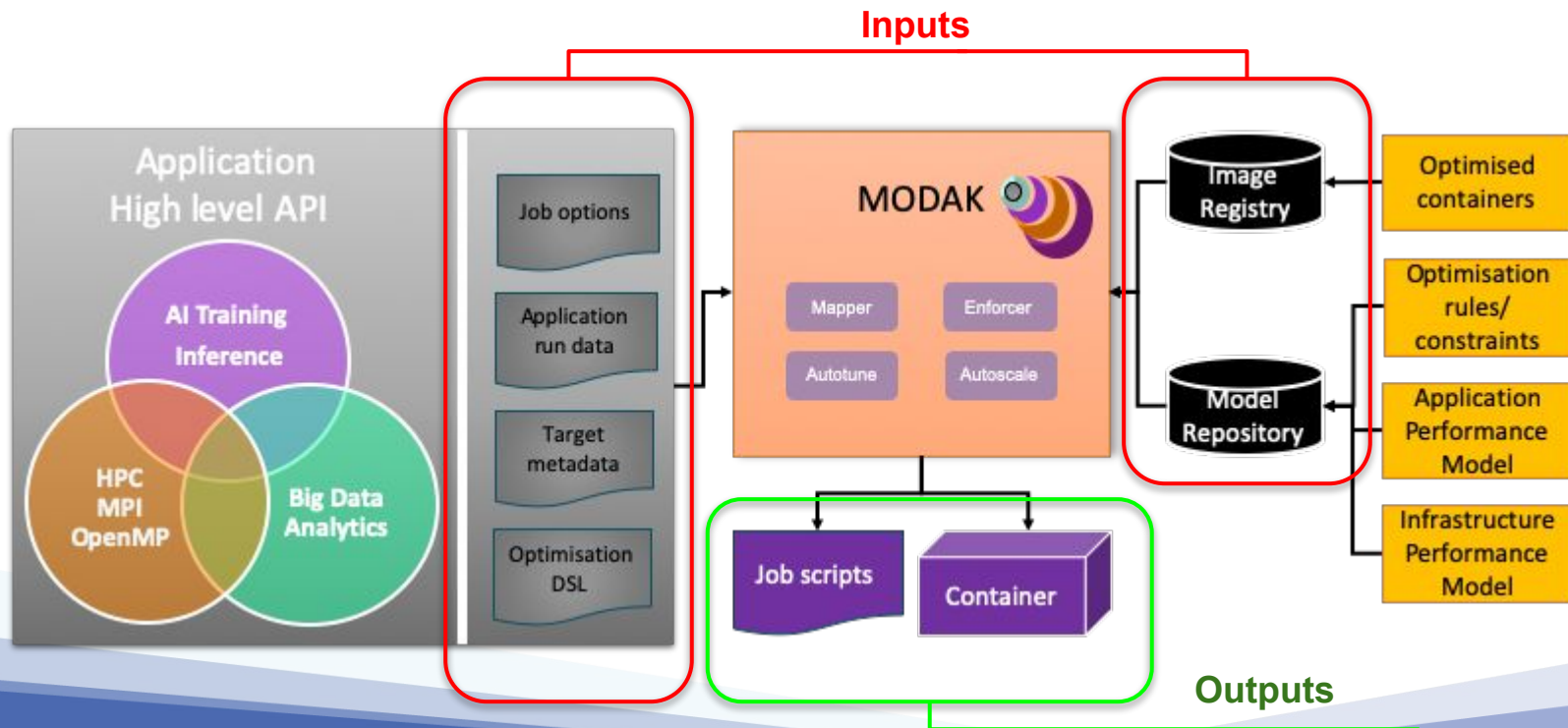
```
probabilistic-mapping-job:  
type: sodalite.nodes.hpc.job.torque  
requirements:  
  host:  
    node: hpc-wm-torque  
  configured_job:  
    node: probabilistic-mapping-job-config  
dependency:  
  node: density-mapping-job-result
```



Full description can be found in IDE GitHub [here](#)

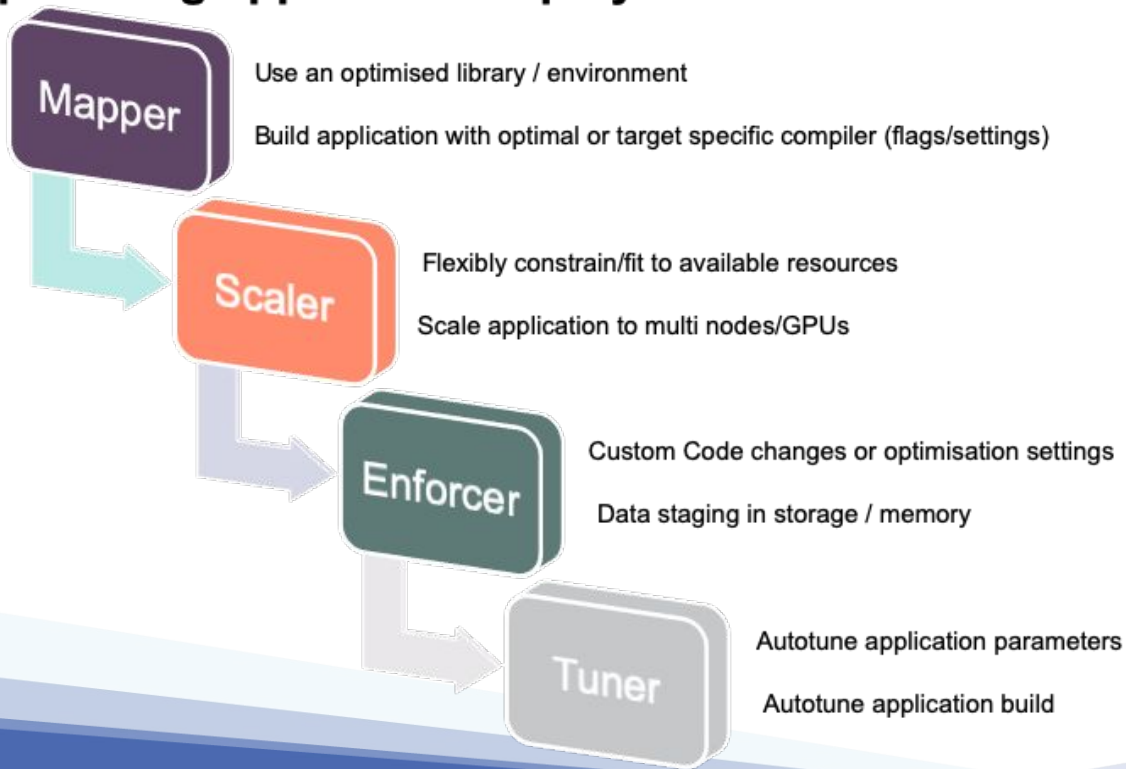
# Application optimization

Support to design time application optimization for HPC



# MODAK Components

## Optimising application deployment





# MODAK API example

Response:

optimised container image  
+  
job script

```
1- |
2- |
3- | "job":{
4- |   "job options": {
5- |     "job_name": "solver",
6- |     "wall_time_limit": "1:00:00 ",
7- |     "node_count": 2,
8- |     "core_count": 40,
9- |     "process_count_per node": 40,
10- |    "standard_output_file": "file.out",
11- |    "standard_error_file": "file.err",
12- |    "combine_stdout_stderr": true,
13- |    "request_event_notification": "abe",
14- |    "email_address": "tokmakov@hlrs.de"
15- |  },
16- |  "application": {
17- |    "app_tag": "solver_clinicalUC",
18- |    "app_type": "hpc",
19- |    "executable": "${ASTER_ROOT}/14.4/bin/aster ",
20- |    "arguments": "${ASTER_ROOT}/14.4/lib/aster/Execution/E_SUPERV.py -commandes fort.1 --num_job=1432 --memjeveux=8192.0 --tpmax=3600.0",
21- |    "build": {
22- |      "src": "https://www.code-aster.org/FICHIERS/aster-full-src-14.4.0-1.noarch.tar.gz",
23- |      "build_command": "python3 setup.py install\n"
24- |    },
25- |    "optimisation": {
26- |      "enable_opt_build": true,
27- |      "enable_autotuning": true,
28- |      "app_type": "hpc",
29- |      "opt_build": {
30- |        "cpu_type": "x86",
31- |        "acc_type": ""
32- |      },
33- |      "autotuning": {
34- |        "tuner": "cresta",
35- |        "input": "dsl text"
36- |      },
37- |      "app_type-hpc": {
38- |        "config":{
39- |          "parallelisation": "mpi"
40- |        },
41- |        "data":{
42- |          "location": "L1L2_NonLinear_prepared.tar.gz"
43- |        },
44- |        "parallelisation-mpi": {
45- |          "library": "mpich",
46- |          "version": "3.14",
47- |          "scaling_efficiency": 0.75
48- |        }
49- |      }
50- |    }
51- |  }
52- | }
```

Job parameters - converts into PBS or Slurm job script parameters

Parameters of how to build and execute application

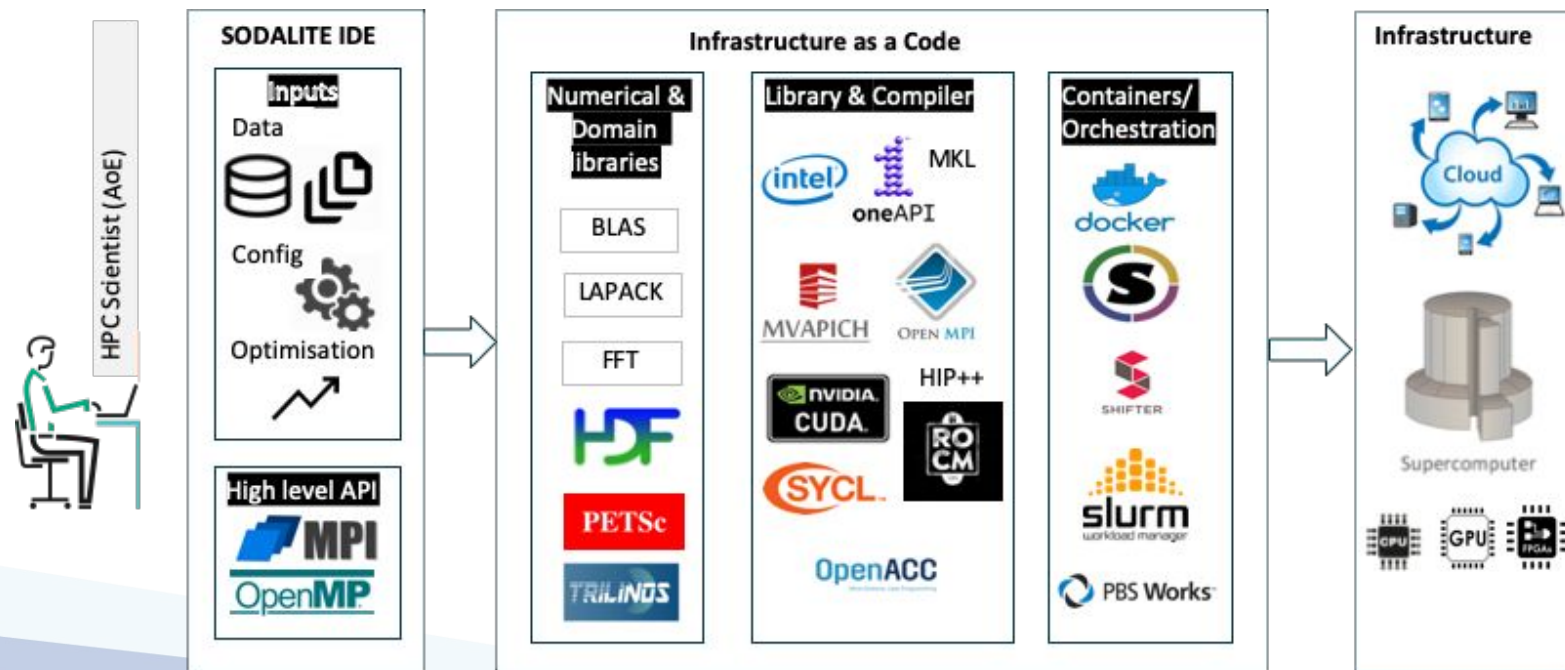
Optimisation parameters - specifying e.g. application type "hpc", parallelisation, CPU architecture, autotuning

# MODAK generated job script

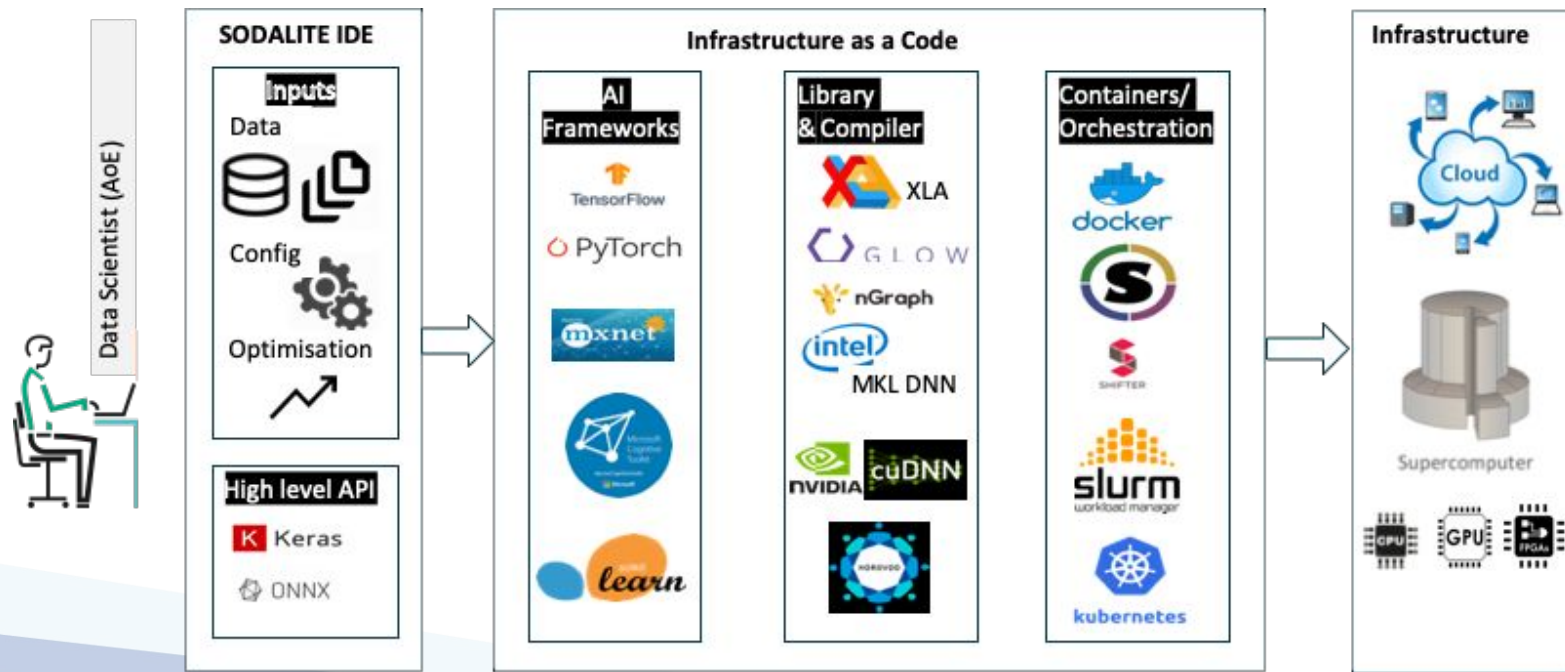


```
1 #PBS -S /bin/bash
2 ## START OF HEADER ##
3 #PBS -N solver
4 #PBS -l walltime=1:00:00
5 #PBS -l nodes=2:ppn=40
6 #PBS -l procs=40
7 #PBS -o file.out
8 #PBS -e file.err
9 #PBS -j oe
10 #PBS -m abe
11 #PBS -M tokmakov@hlrs.de
12 ## END OF HEADER ##
13 cd $PBS_O_WORKDIR
14 export PATH=$PBS_O_WORKDIR:$PATH
15
16 ## START OF TUNER ##
17 file=solver_20201116190135_tune.sh
18 if [ -f $file ] ; then rm $file; fi
19 wget --no-check-certificate https://storage.googleapis.com/modak-bucket//modak/solver_20201116190135_tune.sh
20 chmod 755 solver_20201116190135_tune.sh
21
22 singularity exec $SINGULARITY_DIR/mpich_ub1804_cuda101_mpi314_gnugprof.sif solver_20201116190135_tune.sh
23 ## END OF TUNER ##
24
25 wget --no-check-certificate https://www.code-aster.org/FICHIERS/aster-full-src-14.4.0-1.noarch.tar.gz
26
27 singularity exec $SINGULARITY_DIR/mpich_ub1804_cuda101_mpi314_gnugprof.sif python3 setup.py install
28
29
30 export OMP_NUM_THREADS=1
31 mpirun -np 40 singularity exec $SINGULARITY_DIR/mpich_ub1804_cuda101_mpi314_gnugprof.sif \
32     ${ASTER_ROOT}/14.4/bin/aster ${ASTER_ROOT}/14.4/lib/aster/Execution/E_SUPERV.py -commandes fort.1 --num_job=1432 --memjeveux=8192.0 --tpmax=3600.0
```

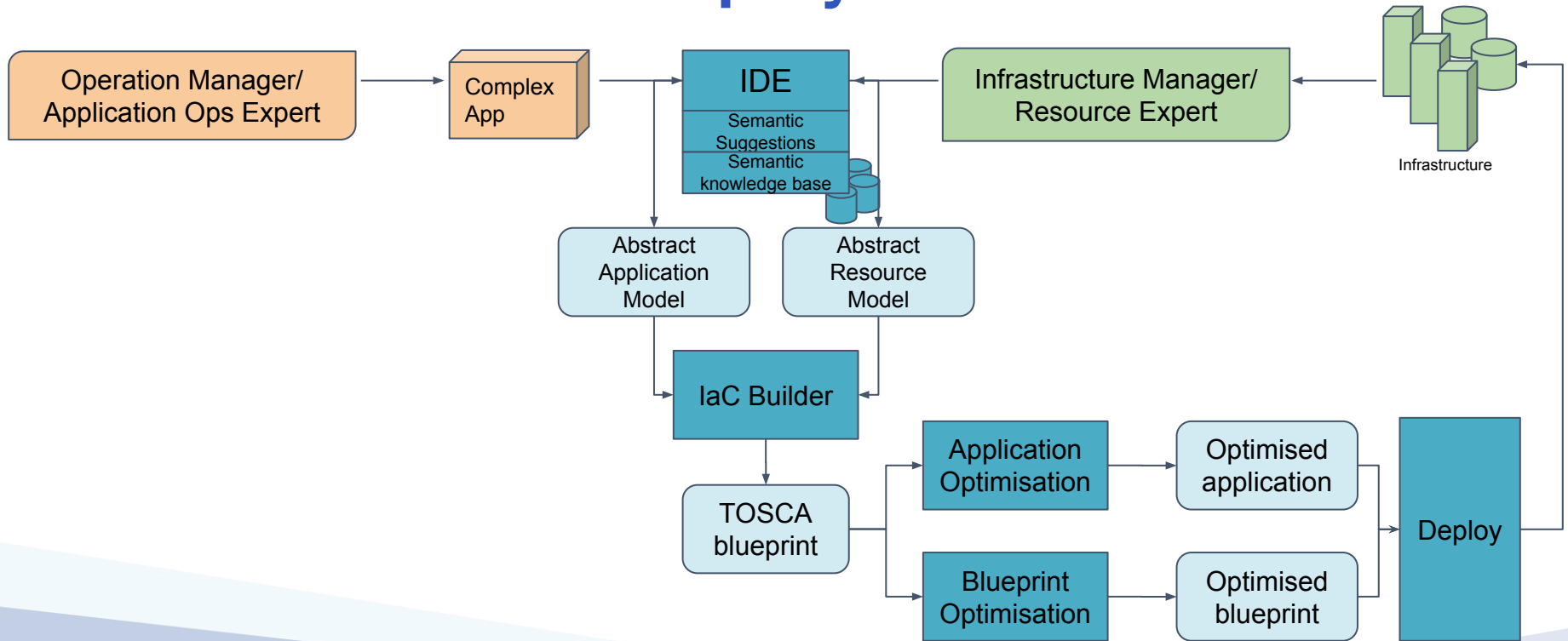
# Optimisation abstraction for Traditional HPC (MPI)



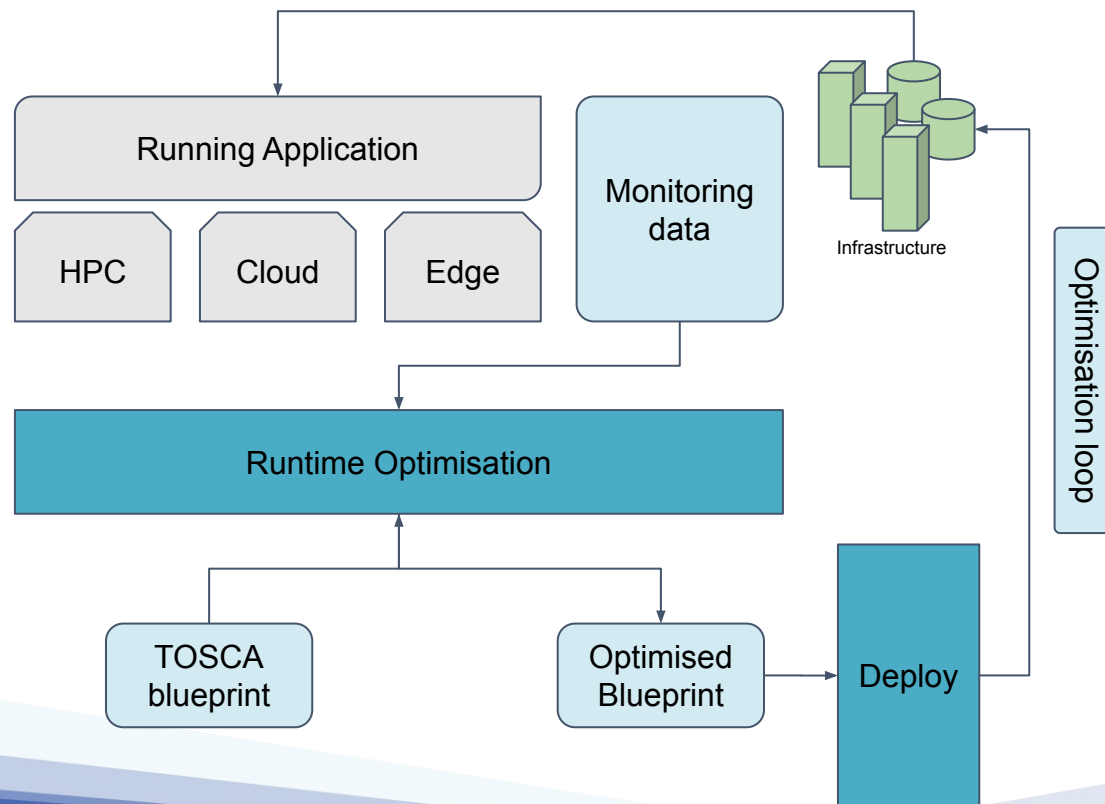
# Optimisation abstraction for AI Training



# The SODALITE Deployment



# The SODALITE Runtime



# Performance Optimisation results



Optimisation results for AI training and HPC deployments with graph compilers and Singularity containers

- For **AI training**
  - **17%** speedup using custom built optimised containers
  - up to a **30%** speedup using graph compilers.
- For traditional **HPC** the work is ongoing (Solver optimisation)
  - Performance with singularity **containers** comparable to native build (up to **6%** speedup)
- Presented talk at [Supercomputing Frontiers](#), Warsaw (March 23 – 25, 2020)
- Presented poster in [ISC-HPC](#) (June 22 – 25, 2020), Frankfurt
- Paper on *Optimising AI Training Deployments using Graph Compilers and Containers* accepted at 2020 [IEEE High Performance Extreme Computing Conference \(HPEC\)](#) 22 - 24 September 2020
- Submitted paper on *MODAK – an Optimiser for HPC and AI training deployments in software defined infrastructures* to The [2020 International Conference on High Performance Computing & Simulation](#) (HPCS 2020)



# Summary



SODALITE outcome already helps Virtual Clinical Trials in biomechanical simulations in moving the process towards production-like environments:

- + Increase the **effectiveness** of component deployment
  - assisted via **IDE**, automated via **orchestrator**
- + Ease the **adaptation** and **optimisation** for different hardware/software platforms
  - **MODAK** and resource models provided abstraction
- + **Lower the efforts** for component **integration**
  - incorporated components and dependencies (container images, data, artifacts) into the **workflow**
- + **Lower the efforts** for **data management**
  - **data management** as part of workflow

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# Links



[Website](http://www.sodalite.eu) - **www.sodalite.eu**



[GitHub Page](#) - **SODALITE-EU**



[Docker Hub](#) - **sodaliteh2020**



[YouTube Channel](#) - **Sodalite H2020**



[Linkedin Page](#) - **sodalite-eu**



[Twitter](#) - **@SODALITESW**



# Sodalite



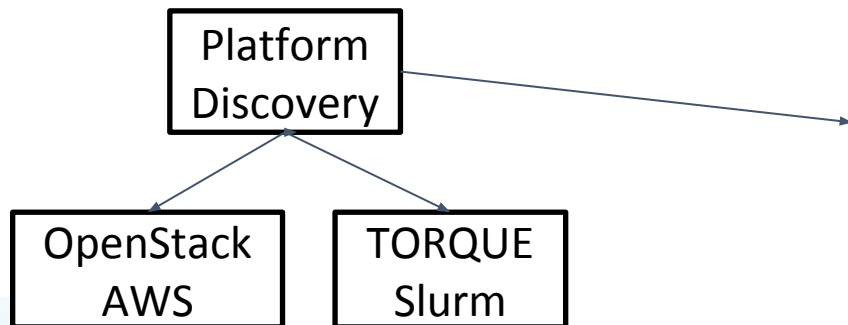
This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 825480.

# Backup slides

# Automated discovery of resources



- Automatic discovery and modeling of new infrastructural resources into IaC



```
sodalite.nodes.hpc.resources.torque:  
  derived_from: toasca.nodes.Compute  
  properties:  
    name:  
      type: string  
      default: h1rs_testbed  
    total_gpus:  
      type: integer  
      default: 5  
    total_nodes:  
      type: integer  
      default: 5  
    total_cores:  
      type: integer  
      default: 200
```

# Runtime deployment optimization

